

Parallelizable Hashing



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Software vs. Hardware

- Majority of the discussion (rightfully) driven by software implementations, however, let us not forget about hardware

Analogies:

Software: 1) SIMD

2) multicores

Hardware: 1) pipelined architectures 2) multi-unit architectures

Differences:

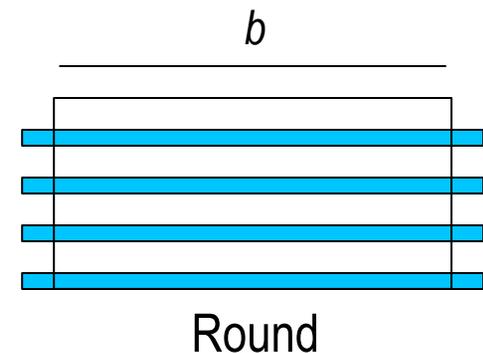
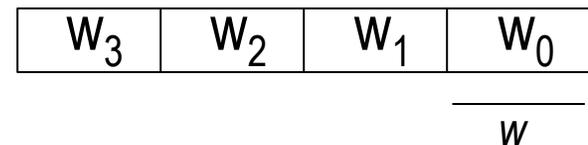
SIMD

- parallelize elementary word operations (ADD, SHIFT, ROTATE, etc.)
- operate on words

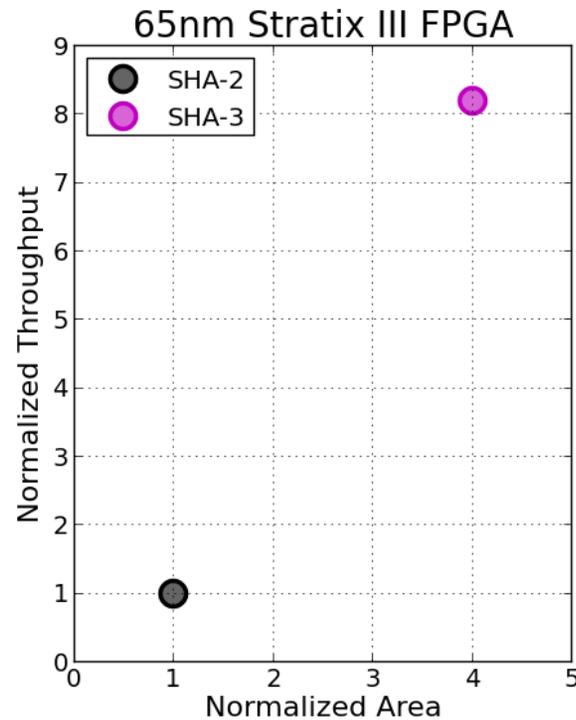
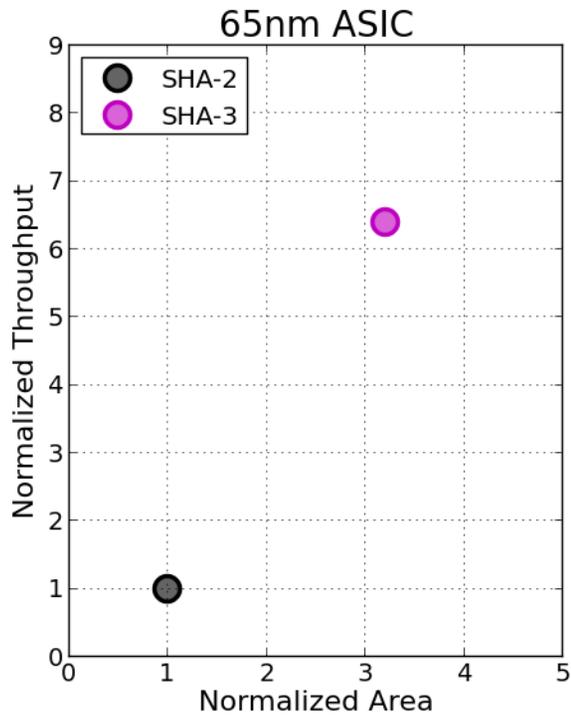
Pipelined architectures

- parallelize stages of the algorithm rounds
- operate on entire message blocks

SIMD register

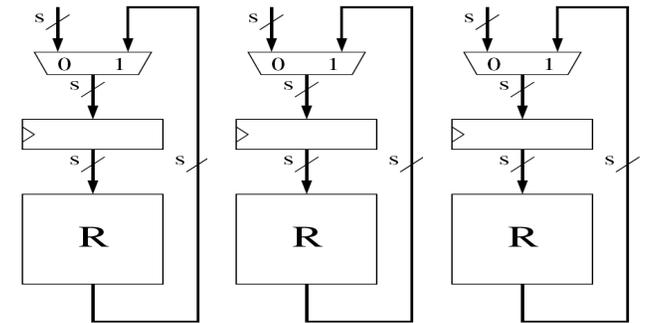


SHA-3 vs. SHA-2 in Hardware

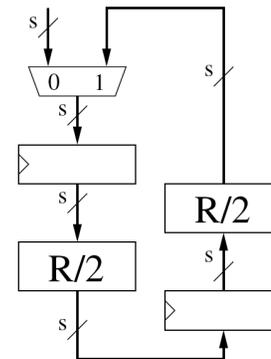


In hardware:

**SHA-3: 6-8 times faster
3-4 times bigger**



SHA-2 more suitable for multi-unit architecture and thus segmenting.



SHA-3 more suitable for pipelining and thus interleaving.

Suggested Approach

- Common standard suitable for SHA-2 and SHA-3
- Segmenting + interleaving
 - **SW: multicores with SIMD**
 - **HW: multi-unit architecture with pipelined units**

with an option of reduction to

- interleaving only (**SW: SIMD; HW: pipelined architecture**)
- segmenting only (**SW: multicore; HW: multi-unit architecture**)
- sequential operation (**SW: single core, no SIMD;**
HW: sequential architectures)

Supported Parameters

Number of lanes:

SW: determined by the ratio $\text{register_size_in_SIMD}/\text{word_size_in_SHA}$

- $\text{register_size_in_SIMD} = 64, 128, 256, 512$
- $\text{word_size_in_SHA} = 32, 64$
- $\#\text{lanes} = 1, 2, 4, 8, 16, 32$

HW: determined by the number of pipeline stages

- not limited to powers of 2
- not likely to exceed 16

Number of segments:

SW: determined by the number of available cores

- number of cores in modern microprocessors = 1, 2, 4, 6, 8, 10, or more

HW: determined by the number of units working in parallel

- limited only by the area budget

Size of segments (no need to specify):

SW, HW: minimum size providing close to maximum performance gain

- may need to be determined experimentally

Used Parameters

Single-user applications

(e.g., integrity of hard drives, remote storage):

- off-line benchmarking with parameters supported by implementation
- choosing the best parameters.

Multi-user applications

(e.g., integrity of messages, digital signatures):

- off-line benchmarking with parameters supported by implementation
- ranking of parameter sets
- negotiating a parameter set with other user(s) based on
 - intersection of user sets
 - best compromise *or* best set for the weakest node.

Other Loose Thoughts

- **Allowing parallelized SHA-2 in HMAC**
- **Treating current sequential SHA-3 and SHA-2 as special cases of the parallelized standardized hash (number of lanes = 1, number of segments = 1)**
- **Dealing with legacy implementations (e.g., those hashing multiple messages in parallel)**
- **The effect of vectored I/O (scatter/gather I/O)**
- **Redefining tree hashing to take advantage of parallelized hashing**